P.A.R.T.S

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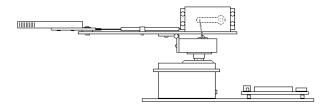
Issue # 12



ARMBOT:

Several months ago I decided to put together a robotic arm to use with the BOTBoard. The design goal was to keep it as simple - simple - simple. Not to mention cheap. The arm I came up with has 3 axis's of movement. It can rotate left and right, lift up and down, and open and close the gripper. The arm uses three unmodified RC servo's that are controlled by a 68HC11 on a BOTBoard. The entire arm can be put together in a couple of hours.

The arm is lots of fun to play with. It's challenging to program the arm to pick up objects. The best user interface might be an analog joystick plugged into the AD ports on the BOTBoard and converted into a position. The ARMBOTs forearm can be easily mounted on any robot..



I have put together a partial kit and instructions for the ARMBOT. The kit includes all the custom plastic pieces needed to build the arm. The manual includes parts list, diagrams, drilling and assembly instructions.

The partial kit with the arm, shoulder mount, shoulder hinge, base platform, mounting brackets and other pieces, including the manual, is only \$12.95.

Basic Stamp vs. 68HC11:

Like other gearheads, I have been wondering what this Basic Stamp thing is all about. I like to use the 68HC11 in my robot projects so I wanted to see what the Basic Stamp could offer against the 68HC11.

Here is a simple chart that gives some comparisons.

	PIC Basic Stamp	MC68HC11A1
CPU Speed	4mhz to 20mhz	2mhz
1		
Program Speed / Sec.	~ 2000	~ 1000000
Programming	BASIC	Assembly
Language		
Easy of programming	Very Easy	Not Easy
I/O Lines	8 lines	38 lines
Resources	A/D and PWM in	8 A/D and 5 timers, 4
	software	PWM in hardware.
Cost for Board *	~ \$40	~ \$25
Cost of Chip *	~ \$20	~ \$5
Development system	~\$100	~ FREE
Current and Voltage	3-6v - 2ma	5v - 15ma
RAM and EEPROM	16 / 256	256 / 512
* Prices may vary!		

Meeting Changes:

The Multinomah County Library is remoldeling, and after August will no longer have public meeting rooms. So a search is on for a PARTS meeting place. I found that ITT Technical Institute is very interested in hosting a meeting room for our group. If you have any thoughts on the matter, give me a call. Also spread the word about PARTS. Lets get this club moving!

Next Issue: Solor Roller Robot, build a robot to race around in the sun.

Other Robotics Clubs

Atlanta Hobby Robotics Association P.O. Box 2050 Stone Mountain, GA 30086 bbs: Robots R4U 404.978.7300

The Robot Group PO Box 164334 Austin, TX 78701 tel: 512.794.9105 net: <robot-group@cs.uteaxs.edu>

Austin Robotics Group 608 Garden Path Cove Round Rock, TX 78736 tel: 512.244.6707

Connecticut Robotics Society P.O. Box 127 Canaan CT 06018 tel: 203.824.0542

The Dallas Personal Robotics Group P.O. Box 1626 Hurst, TX 76053

LA Area Robotics and Automation Group <la-rgroup@cad.ucla.edu> Los Angeles, CA

Robot Society of Southern CA 10471 S. Brookhurst Anaheim, CA 92804 tel: 714.535.8161

Robotics Club of Maryland Computer Science Dept. A.V. Williams Bldg. (115) University of Maryland College Park, Md. 20742-3255 contact: Stephen Klueter, President net: <steveck@Glue.umd.edu> The Robotics Society of America PO Box 1205 Danville, CA 94526-1205 tel:415.550.0588 fax: 415.550.0411

bbs: 415.648.6427 (supports 14.4Kb)

net: <bsmall@sfrsa.com>

Seattle Robotics Society P.O. Box 30668 Seattle, WA 98103-0668

tel: 206.782.5989

SRS also operates a bbs: 206.633.2905

Triangle Amateur Robotics Club P.O. Box 17523 Raleigh, NC 27619 tel: 919.782.8703

net: sasrer@unx.sas.com (Rodney Radford)